





Autopilot, powerful Al Mission Computer and 4G/5G connectivity in a compact, embedded design for any UAV type.







KEY FEATURES

- ✓ Helps to reduce engineering and development costs, reduces time to market and risks
- ✓ Based on open source software (Linux, PX4.) Ardupilot) and the latest industry standards
- Easy scale from prototype to mass production
- Develop your own apps and integrations
- Powers any type of UAV including multirotors, fixed wings, VTOLs
- ✓ Aligned with Blue sUAS architecture
- Designed and manufactured in the UK

ENTERPRISE DRONE ECOSYSTEM

Access the enterprise drone ecosystem with real time remote workflows, planning, flight analytics, assets management. Connect your apps with API.

IN THE DRONE



SMARTAP AIRLINK

ON THE GROUND



SMARTAP GCS

IN THE CLOUD



YOUR BUSINESS

SKY-DRONES CLOUD



GO TO MARKET FASTER

AIRLink stands for Artificial Intelligence & Remote Link. The unit includes cutting-edge drone autopilot, Al Mission Computer and LTE connectivity unit. Start your enterprise drone operations with AIRLink and reduce the time to market from years and months down to weeks.



1. START WITH PROTOTYPE

Start with AIRLink Enteprise, build a prototype to verify your design and business idea.

2. GO TO MARKET



Roll out to market faster and start scaling up the production with AIRLink Core. Deeper integration, custom features and benefit from high volume discounts.

3. SCALE UP

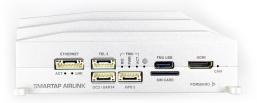
License AIRLink Reference Design and manufacture at scale. Maintain the deployment process with the Cloud including deployment on our own server.

See reverse for detailed technical secification



SMARTAP AIRLINK

INTERFACES



- Ethernet port with power output
- Telemetry port
- Second GPS port
- Spare I2C / UART port
- Flight controller USB Type-C
- Micro SIM Card
- HDMI Input port (Payload camera)



KEY FEATURES

✓ Multiple cameras support

✓ Remote software updates

✓ Autopilot + Al Mission Computer + 4G/5G

✓ BVLOS flight ready with UTM support

✓ Cloud connectivity via WiFi or 4G/5G

✓ Develop and deploy your own apps

✓ Vibration-dampened & temperature-stabilized IMU ✓ Open source software (PX4 / APM) + Linux

✓ Real time video streaming with multiple video feeds

Onboard video processing and object tracking



- Main telemetry port
- CSI camera input
- CAN 1
- CAN 2



- Power input w/ voltage & current sensing
- Al Mission Computer micro SD card
- Flight Controller micro SD card
- Al Mission Computer USB Type-C
- PPM Input, SBUS Output, RSSI monitor

- SBUS input
- 16 PWM output channels
- 2x LTE antenna sockets (MIMO)
- WiFi Antenna socket (AP & Station modes)

TECHNICAL SPECIFICATIONS

| Naviagtion | Accelerometers, Gyroscopes, |
|--------------|-----------------------------------|
| | Magnotometer, GNSS |
| | Rangefinders, Lidars |
| | Optical Flow, Visual |
| IMU | 3x-Redundant |
| | Vibration Dampened |
| | Temperature Stabilized |
| GNSS | GPS, GLONASS, Galileo |
| | BeiDou, |
| | RTK (option) |
| Flight Modes | Manual, Stabilize, GNSS-Assisted, |
| | Autonomous Waypoints, Guided |
| | Terrain Following |
| Flight Logs | SD Card |
| | up to 256GB |
| Temperature | Operating from -40°C up to +50°C |
| ECCN | 7E994 |
| SUPPORTED VE | HICLE TYPES |

| SUPPORTED VEHICLE TYPES | |
|-------------------------|-----------------------------------------------|
| Multirotor | Quad, Hex, Octo Dodeca, Coaxial, Y |
| Fixed Wing | Ailerons, Flaps, Elevons V-Tail, H-Tail |
| VTOL | Tailsitter Multicopter Planes Tiltrotor |
| WEIGHT AND DIMEN | ISIONS |

Module Weight Module Dimensions

FLIGHT CONTROLLER

| Processor | STM32F765 |
|-----------|-------------------------------------------------------------------------------------------------------------------|
| Frequency | 216 MHz |
| Flash | 2MB |
| RAM | 512 kB |
| IMU | 3 Accelerometers, 3 Gyroscopes, |
| | 3 Magnetometers, 2 Barometers |
| Ethernet | 10/100 Mbps |
| | LAN with AI Missioni Computer |
| UARTs | Telemetry 1, Telemetry 2 (Al Mission Computer), Telemetry 3, GPS 1, GPS 2, Extra UART, Serial Debug Console |
| CAN | CAN 1, CAN 2 |
| USB | MAVLink Serial Console |
| RC Input | SBUS, RSSI, PPM, Spektrum |
| PWM Out | 16 Channels |

| CONNE | CTIVITY MODULE |
|-----------|----------------------------------------------------------|
| Туре | 4G |
| | UMTS/HSPA(+), GSM/GPRS/EDGE 5G available as an option |
| SIM Cards | Integrated eSIM External MicroSIM card slot |
| Antenna | 2x2 MIMO |
| Bands | EMEA, North America, Australia, Japan, Other |
| DATA T | RANSFER |
| Downlink | 150 Mbps |
| Uplink | 50 Mbps |

AI MISSION COMPUTER

| CPU | 6-Core: Dual-Core Cortex-A72 |
|-------------|--------------------------------------------------|
| | Quad-Core Cortex-A53 |
| GPU | Mali-T864, OpenGL ES1.1/2.0/3.0/3.1 |
| VPU | 4K VP8/9 |
| | 4K 10bits H265/H264 60fps Decoding |
| Power | Software Resei |
| | RTC Wake-Up |
| | Sleep Mode |
| RAM | Dual-Channel 4GB LPDDR4 |
| Storage | 16GB eMMC 5.1 Flash |
| | MicroSD up to 256GE |
| Ethernet | 10/100/1000 Native Gigabi |
| Wireless | 802.11a/b/g/n/ad |
| (WiFi/BT) | Bluetooth |
| | 2x2 MIMC |
| USB | USB 3.0 Type 0 |
| Video | 4-Lane MIPI CSI (FPV Camera |
| | 4-Lane MIPI CSI with HMDI Input (Payload Camera |
| | Carriera |
| VIDEO | |
| Camera | FPV MIPI-CSI Camera Input (included |
| Interfaces | Payload HDMI Camera Inpu |
| | Ethernet IP Based Cameras |
| | USB Cameras |
| HDMI Input | Native Support with Integrated FPGA Converter |
| Video Codec | 1080p 60fps H.264/265 |

L103 x W61 x H37mm